

19-2

Describe how to implement this algorithm using binomial heaps to manage the vertex and edge sets. Do you need to change the representation of a binomial heap? Do you need to add operations beyond the mergeable-heap operations given in Figure 19.1? Give the running time of your implementation.

I'm not going to explain what a minimum-spanning-tree is (I assume we've all taken discrete math), so this is a possible solution for a graph $G = (V,E)$:

- Find the root x with the minimum key in the root list of E_i , then remove x from E_i .
- Make a binomial heap from E_j .
- Reverse the order of x 's children and then set the head of E_j to the head of the resulting list.
- Set heap H equal to the union of the two binomial heaps E_i, E_j ,
- Return x .

Each step of this algorithm takes $O(\lg(n))$ time, so the end result is $O(\lg(n))$.

22.1-1

Given an adjacency-list representation of a directed graph, how long does it take to compute the out-degree of every vertex? How long does it take to compute the in-degrees?

The out-degree of each vertex can be determined by analyzing each node in the adjacency list once: $O(E)$.

The in-degree of each vertex can be determined by analyzing each element in the adjacency list so we have $O(E + V)$.

22.1-2

Give an adjacency-list representation for a complete binary tree on 7 vertices. Give an equivalent adjacency-matrix representation. Assume that vertices are numbered from 1 to 7 as in a binary heap?

An adjacency-list representation for a complete binary tree may look like this:

```
[1]->[2]->[3]->x  
[2]->[4]->[5]->x  
[3]->[6]->[7]->x  
[4]->x  
[5]->x  
[6]->x
```

An equivalent adjacency matrix matrix is the following:

X	1	2	3	4	5	6	7
1	X	1	1	0	0	0	0
2	1	X	0	1	1	0	0
3	1	0	X	0	0	1	1
4	0	1	0	X	0	0	0
5	0	1	0	0	X	0	0

6	0	0	1	0	0	X	0
7	0	0	1	0	0	0	X

22.1-3

Describe efficient algorithms for computing G^T from G , for both the adjacency list and adjacency-matrix representations of G . Analyze the running times of your algorithms.

The transpose of the adjacency matrix can simply be done by swapping the indices of the matrix. This is accomplished by setting $Matrix[i][j]$ to $TransposeMatrix[j][i]$. Therefore this is $O(V^2)$.

The transpose of the adjacency list is done by redrawing the graph in reverse order. A possible algorithm would be:

```

Transpose(V,E, AList)
{
    for each v in V
        for each e in AList[v]
            TransposeList[e].add(v);
    return TransposeList
}

```

The running time of this algorithm is $O(V + E)$.

References

Third edition of the textbook and solution manual
http://en.wikipedia.org/wiki/Directed_graph#Indegree_and_outdegree